Dual Display, PID Control Temperature Controller

### Features
- Realizes ideal temp. controlling with newly developed PID control algorithm and 100ms high speed sampling
- Built-in relay output or SSR drive output selectable
  - Enables to phase control and cycle control with SSR drive output (SSRP function)
  - Dramatically increased visibility using wide display part
  - Enhanced convenience of wiring and maintenance by connector plug type (TCN4S-P)
- Mounting space saving with compact design
  - Approx. 38% reduced size compared with existing model (depth-based)

### Ordering Information

<table>
<thead>
<tr>
<th>Series</th>
<th>TCN4S</th>
<th>TCN4M</th>
<th>TCN4H</th>
<th>TCN4L</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power supply</td>
<td>AC power</td>
<td>100-240VAC ~ 50/60Hz</td>
<td>AC/DC power</td>
<td>24VAC ~ 50/60Hz, 24-48VDC</td>
</tr>
<tr>
<td>Allowable voltage range</td>
<td>90 to 110% of rated voltage</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Power consumption</td>
<td>AC power</td>
<td>Max. 5VA (100-240VAC 50/60Hz)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Display method</td>
<td>7-segment (PV: red, SV: green), Other display (green, red) LED</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Character size</td>
<td>PV (W×H)</td>
<td>7.0×15.0mm</td>
<td>9.5×20.0mm</td>
<td>7.0×14.6mm</td>
</tr>
<tr>
<td>SV (W×H)</td>
<td>5.0×9.5mm</td>
<td>7.5×15.0mm</td>
<td>6.0×12.0mm</td>
<td>7.0×14.0mm</td>
</tr>
<tr>
<td>Input type</td>
<td>RTD</td>
<td>K(Ω), J(Ω), L(Ω), T(Ω), R(PR), S(PR)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Display accuracy</td>
<td>At room temperature (23°C ±5°C); (PV ±0.5% or ±1°C, select the higher one) ±1-digit</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Control output</td>
<td>Relay</td>
<td>250VAC ~ 3A, 30VDC = 3A, 1a</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Alarm output</td>
<td>AL1, AL2 Relay output: 250VAC 1A 1a</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Control method</td>
<td>ON/OFF control, P, PI, PD, PID control</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Hysteresis</td>
<td>1 to 100°C/F (0.1 to 50.0°C/F) variable</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Proportional band (P)</td>
<td>0.1 to 999.9°C/F</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Integral time (I)</td>
<td>0 to 9999 sec</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Derivative time (D)</td>
<td>0 to 9999 sec</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Control period (T)</td>
<td>0.5 to 120.0 sec</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Manual reset</td>
<td>0.0 to 100.0%</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Sampling period</td>
<td>100ms</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Specifications

1: Only for TCN4S model.
2: In case of the AC voltage model, SSR drive output method (standard ON/OFF control, cycle control, phase control) is available to select.

Please read "Safety Considerations" in the instruction manual before using.
### Specifications

<table>
<thead>
<tr>
<th>Series</th>
<th>TCN4S</th>
<th>TCN4M</th>
<th>TCN4H</th>
<th>TCN4L</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dielectric strength</td>
<td>AC Power</td>
<td>2,000VAC 50/60Hz for 1 min (between input terminal and power terminal)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>AC/DC power</td>
<td>1,000VAC 50/60Hz for 1 min (between input terminal and power terminal)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Vibration</td>
<td>0.75mm amplitude at frequency of 5 to 55Hz in each X, Y, Z direction for 2 hours</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Relay life cycle</td>
<td>Mechanical</td>
<td>OUT: over 5,000,000 times, AL1/2: Over 5,000,000 times</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Electrical</td>
<td>OUT: over 200,000 times (250VAC 3A resistive load) AL1/2: over 300,000 times (250VAC 1A resistive load)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Insulation resistance</td>
<td>Over 100MO (at 500VDC megger)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Noise immunity</td>
<td>±2kV R-phase, S-phase the square wave noise (pulse width: 1us) by the noise simulator</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Memory retention</td>
<td>Approx. 10 years (when using non-volatile semiconductor memory type)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Environment resistance</td>
<td>Rated at no freezing or condensation</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

#### TCN4 Series

- TCN4 Series has selectable control output; Relay output, and SSR drive output. AC/DC voltage type does not have SSRP function.
- Use crimp terminals or terminals of size specified below.

<table>
<thead>
<tr>
<th>Terminal number</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 to 8</td>
<td>6</td>
<td>Max. 1.7</td>
<td>Max. 3.7</td>
</tr>
<tr>
<td>9 to 11</td>
<td>6 to 8</td>
<td>Max. 2.1</td>
<td>Max. 4.2</td>
</tr>
<tr>
<td>12 to 14</td>
<td>6 to 8</td>
<td>Max. 1.5</td>
<td>Max. 3.5</td>
</tr>
</tbody>
</table>

#### TCN4S

- SSR OUT: 12VDC ±2V 20mA Max.
- SOURCE: 100-240VAC 5VA 50/60Hz, 24V AC 5VA 50/60Hz, 24-48VDC 3W

#### TCN4M

- SSR OUT: 12VDC ±2V 20mA Max.
- SOURCE: 100-240VAC 5VA 50/60Hz, 24V AC 5VA 50/60Hz, 24-48VDC 3W

- Relay OUT: 250VAC 3A 1a 30VDC 3A 1a

#### TCN4H/L

- SSR OUT: 12VDC ±2V 20mA Max.
- SOURCE: 100-240VAC 5VA 50/60Hz, 24V AC 5VA 50/60Hz, 24-48VDC 3W

- Relay OUT: 250VAC 3A 1a 30VDC 3A 1a

- AL1 OUT: 250VAC 1A 1a
- AL2 OUT: 250VAC 1A 1a

1: Power supply
- AC power: 100-240VAC 5VA 50/60Hz
- AC/DC power: 24VAC 5VA 50/60Hz, 24-48VDC 3W

2: The weight includes packaging. The weight in parenthesis is for unit only.

- Environment resistance is rated at no freezing or condensation.
Dual Display, PID Control

**Dimensions**

**TCN4S**

**TCN4S-P**

**TCN4M**

**TCN4H**

**TCN4L**

**Panel cut-out**

<table>
<thead>
<tr>
<th>Size</th>
<th>Series</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>TCN4S</td>
<td>Min. 65</td>
<td>Min. 65</td>
<td>45°</td>
<td>45°</td>
<td></td>
</tr>
<tr>
<td>TCN4M</td>
<td>Min. 90</td>
<td>Min. 90</td>
<td>68°</td>
<td>68°</td>
<td></td>
</tr>
<tr>
<td>TCN4H</td>
<td>Min. 65</td>
<td>Min. 115</td>
<td>45°</td>
<td>92°</td>
<td></td>
</tr>
<tr>
<td>TCN4L</td>
<td>Min. 115</td>
<td>Min. 115</td>
<td>92°</td>
<td>92°</td>
<td></td>
</tr>
</tbody>
</table>

**Bracket**

- **TCN4S Series**

- **TCN4M, TCN4H, TCN4L Series**
**Dimensions**

- **Terminal cover (sold separately)**
  - RSA-COVER (48×48mm)
  - RMA-COVER (72×72mm)
  - RHA-COVER (48×96mm)
  - RLA-COVER (96×96mm)

**Unit Description**

1. **Present value (PV) display (red)**
   - RUN mode: Currently measured value (PV) display.
   - Parameter setting mode: Parameter display.

2. **Setting value (SV) display (green)**
   - RUN mode: Setting temperature value (SV) display.
   - Parameter setting mode: Parameter setting value display.

3. **Control/Alarm output display indicator**
   - OUT: It turns ON when the control output is ON.
   - AL1/AL2: It turns ON when the alarm output is ON.

4. **Auto tuning indicator**: AT indicator flashes by every 1 sec during operating auto tuning.

5. **MODE key**: Used when entering into parameter setting group, returning to RUN mode, moving parameter, and saving setting values.

6. **Adjustment**: Used when entering into set value change mode, digit moving and digit up/down.

7. **Digital input key**: Press [ ] + [ ] keys for 3 sec to operate the set function (RUN/STOP, alarm output reset, auto tuning) in digital input key \(\text{[D1/ D2]}\).

8. **Temperature unit (°C/°F) indicator**: It shows current temperature unit.

**SV Setting**

You can set the temperature to control with [MODE], [ ], [ ], [ ] keys.
Setting range is within SV lower limit value \([L \sim 5U]\) to SV higher limit value \([H \sim 5U]\).

E.g.) In case of changing set temperature from 210°C to 250°C

1. **RUN mode**
2. **SV setting mode**
3. **Check SV**

**Parameter Reset**

Reset all parameters as factory default. Hold the front [ ] + [ ] + [ ] keys for 5 sec, to enter parameter reset \([\text{L-1} \sim \text{L-1}]\) parameter. Select \(\text{L-5}\) and all parameters are reset as factory default. Select \(\text{L-0}\) and previous settings are maintained. If setting parameter lock \([\text{L-01} \sim \text{L-02}]\) or processing auto-tuning, parameter reset is unavailable.
Parameter Group

- **Run mode**: Press any key among [MODE] for 2 sec in Run mode to enter Parameter group 1.
- **Parameter group 1**: AL1 alarm temperature, AL2 alarm temperature, Auto tuning, Proportional band, Integral time, Derivative time, Manual reset, Hysteresis.
- **Parameter group 2**: Input sensor, Temperature unit, Control type, Control output operation, Control output type, SSR drive output method, Control cycle, Control output operation mode, AL1 alarm operation mode, AL2 alarm operation mode, LBA detection band, LBA monitoring time, Alarm output hysteresis, Digital input key, Control output MV in case of input break error, Parameter lock.

- **Parameter setting rules**:
  - Press [MODE] key over 3 sec in any setting group, it saves the set value and returns to RUN mode.
  - If no key entered for 30 sec, it returns to RUN mode automatically and the set value of parameter is not be saved.
  - Press [MODE] key again within 1 sec after returning to RUN mode, it advances of the first parameter of previous setting group.
  - Press [MODE] key to move next parameter.
  - This parameter might not be displayed depending on other parameter settings.
  - Set parameter as 'Parameter group 2 → Parameter group 1 → Setting of set value' order considering parameter relation of each setting group.
  - ※1: It is not displayed for AC/DC power model (TCN4□-22R).
Parameter Group 1

1: Press any key among <, @, #.
2: After checking or changing setting value in each parameter, press MODE key to save and move to next parameter setting.
3: It is displayed when control type parameter [C - \(\alpha\)] of parameter group 2 is set PI d.

Press MODE key for 3 sec to return RUN mode at any parameter.

This parameter might not be displayed depending on other parameter settings.

Setting range: Deviation alarm (-F to S), Absolute value alarm (temperature range)

In case alarm operation mode [AL-1] of Parameter group 2 is AM)\_/SBa\_/BA, no parameters is displayed.

Setting range: 0.1 to 999.9 °C/F

Integral operation is OFF when set value is "0".

Setting range: 0 to 9999 sec

Derivative operation is OFF when set value is "0".

Setting range: 0.0 to 100.0%

It is displayed in P, PD control.

Setting range

- \(K_{CaH}, J_{ICL}, L_{ICL}, T_{CCL}, R_{PR}, S_{RP}, dP_{Th}, C_{USL}: 1 \text{ to } 1000 \degree C/F\)
- \(K_{CaL}, J_{IcH}, L_{ICL}, T_{CCL}, dP_{Th}, C_{USL}: 0.1 \text{ to } 50.0 \degree C/F\)

Parameter Group 2

1: Press any key among <, @, #.
2: After checking or changing setting value in each parameter, press MODE key to save and move to next parameter setting.
3: It is displayed when control type parameter [C - \(\alpha\)] of parameter group 2 is set PI d.

Press MODE key for 3 sec to return RUN mode at any parameter.

This parameter might not be displayed depending on other parameter settings.

Setting range: Refer to 'Input sensor and temperature range'.

If changing input sensor, SV, \(n-\), H-Su, L-Su, AL 1, AL 2, LbAb, LbAb, RHYS parameter values are initialized.

Setting range: -999 to 9999°C/F

If changing temperature unit, SV, \(n-\), H-Su, L-Su, AL 1, AL 2, LbAb, LbAb, RHYS parameter values are initialized.

Setting range: 0.01 to 120.0 sec

Set input digital filter time for average input value affected control, and display value.
Dual Display, PID Control

Setting range: Within the rated temperature range by input sensor \([L - 5u \leq (H - 5u - 1\text{-digit})]\)
※ When changing SV low-limit value, if \(SV < 5u\), SV is initialized as \(L - 5u\).
※ In case of changing input sensor type \([L - \epsilon]\), it changes automatically as max. value of the changed input sensor.

Setting range: Within the rated temperature range by input sensor \([H - 5u \geq (L - 5u + 1\text{-digit})]\)
※ When changing SV high-limit value, if \(SV > H - 5u\), SV is initialized as \(H - 5u\).
※ In case of changing input sensor type \([L - \epsilon]\), it changes automatically as max. value of the changed input sensor.

※ When changing control output operation, \(ErrMV\) is initialized.

※ When changing control type, \(ErrMV\) is initialized (control output MV is below 100%) and \(DI-T\) turns OFF automatically.

※ It is displayed when selecting control output \([\text{OUT}]\) as \(SSR\).
※ It is not displayed for AC/DC power model (TCN4 -22R).

Setting range: 0.5 to 120.0 sec
In case of Relay output \([\text{RLY}]\) of control output \([\text{OUT}]\) it is set as 20.0 sec
In case of SSR drive output \([\text{SSR}]\) of that, it is set as 2.0 sec
※ It is not displayed when SSR drive output \([\text{SSRM}]\) method is set as \(\text{CYCL}, \text{PHAS}\).

※ '0' is set, loop break alarm function is OFF.
※ LBaB is displayed when AL1, AL2 alarm operation mode \([\text{AL-1}, \text{AL-2}]\) is set as \(\text{LBa}\) and \(\text{LBaT}\) is not '0'.

※ Parameter setting values are still possible to check when parameter lock is set.
### Input Sensor and Temperature Range

<table>
<thead>
<tr>
<th>Input sensor</th>
<th>Display</th>
<th>Temperature range (℃)</th>
<th>Temperature range (℉)</th>
</tr>
</thead>
<tbody>
<tr>
<td>K(CA)</td>
<td>KCRH</td>
<td>-50 to 1200</td>
<td>-58 to 2192</td>
</tr>
<tr>
<td></td>
<td>KCRCL</td>
<td>-50.0 to 999.9</td>
<td>-58.0 to 999.9</td>
</tr>
<tr>
<td>J(IC)</td>
<td>JI CH</td>
<td>-30 to 800</td>
<td>-22 to 1472</td>
</tr>
<tr>
<td></td>
<td>JI CL</td>
<td>-30.0 to 800.0</td>
<td>-22.0 to 999.9</td>
</tr>
<tr>
<td>L(IC)</td>
<td>L1 CH</td>
<td>-40 to 800</td>
<td>-40 to 1472</td>
</tr>
<tr>
<td></td>
<td>L1 CL</td>
<td>-40.0 to 800.0</td>
<td>-40 to 999.9</td>
</tr>
<tr>
<td>T(CC)</td>
<td>TCCCH</td>
<td>-50 to 400</td>
<td>-58 to 752</td>
</tr>
<tr>
<td></td>
<td>TCCCL</td>
<td>-50.0 to 400.0</td>
<td>-58.0 to 752.0</td>
</tr>
<tr>
<td>R(PR)</td>
<td>r Pr</td>
<td>0 to 1700</td>
<td>32 to 3092</td>
</tr>
<tr>
<td>S(PR)</td>
<td>s Pr</td>
<td>0 to 1700</td>
<td>32 to 3092</td>
</tr>
<tr>
<td>RTD</td>
<td>DPl100Ω</td>
<td>DPlH</td>
<td>-100 to 400</td>
</tr>
<tr>
<td></td>
<td></td>
<td>DPlL</td>
<td>-148 to 752</td>
</tr>
<tr>
<td></td>
<td>Cus50Ω</td>
<td>CusH</td>
<td>-50 to 200</td>
</tr>
<tr>
<td></td>
<td></td>
<td>CusL</td>
<td>-58.0 to 392.0</td>
</tr>
</tbody>
</table>

### Factory Default

#### SV setting

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Factory default</th>
</tr>
</thead>
<tbody>
<tr>
<td>_</td>
<td>0</td>
</tr>
</tbody>
</table>

#### Parameter group 1

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RL 1</td>
<td>1250</td>
<td>aR</td>
<td><em>OFF</em></td>
<td>L</td>
<td>0000</td>
</tr>
<tr>
<td>RL 2</td>
<td>1250</td>
<td>p</td>
<td>0 100</td>
<td>d</td>
<td>0000</td>
</tr>
</tbody>
</table>

#### Parameter group 2

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
<th>Parameter</th>
<th>Factory default</th>
</tr>
</thead>
<tbody>
<tr>
<td>1u</td>
<td>KCRH</td>
<td>H-5u</td>
<td>1200</td>
<td>b</td>
<td>0200</td>
</tr>
<tr>
<td>1h</td>
<td></td>
<td></td>
<td>a-ft</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1n</td>
<td>P</td>
<td></td>
<td>H-er</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1p</td>
<td>0000</td>
<td></td>
<td></td>
<td></td>
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</tr>
<tr>
<td>1q</td>
<td>000.1</td>
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<td></td>
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<tr>
<td>1m</td>
<td>-050</td>
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</tr>
<tr>
<td>1n</td>
<td>55r3</td>
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<td></td>
<td></td>
</tr>
<tr>
<td>1o</td>
<td>5tnd</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1p</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

*The AC/DC voltage models do not have SSR drive output method [SSrM]. In case of control output [OUT], if set as SSr, it supports only ON/OFF output.

#### Mounting

##### TCN4S (48×48mm) Series

※Mount the product on the panel, fasten bracket by pushing with tools as shown above.

##### Other Series
Functions

© Alarm [RL - 1 / RL - 2]

Set both alarm operation and alarm option by combining. Alarm outputs are two and each one operates individually. When the current temperature is out of alarm range, alarm clears automatically. If alarm option is alarm latch or alarm latch and standby sequence 1/2, press digital input key[+ - ] 3 sec, digital input key[3 - 1] of parameter group 2 set as RL-00, or turn OFF the power and turn ON to clear alarm.

● Alarm operation

<table>
<thead>
<tr>
<th>Mode</th>
<th>Name</th>
<th>Alarm operation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>Deviation high-limit alarm</td>
<td>OFF H ON SV PV 100℃ 110℃ High deviation: Set as 10℃</td>
<td>If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON.</td>
</tr>
<tr>
<td>E</td>
<td>Deviation low-limit alarm</td>
<td>ON H OFF SV PV 90℃ 100℃ Lower deviation: Set as 10℃</td>
<td>If deviation between PV and SV as low-limit is higher than set value of deviation temperature, the alarm output will be ON.</td>
</tr>
<tr>
<td>F</td>
<td>Deviation high/low-limit alarm</td>
<td>ON H ON SV PV 90℃ 100℃ High/Lower deviation: Set as 10℃</td>
<td>If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON.</td>
</tr>
<tr>
<td>G</td>
<td>Absolute value high limit alarm</td>
<td>OFF H ON PV 100℃ 90℃ Absolute-value Alarm: Set as 90℃</td>
<td>If PV is higher than the absolute value, the output will be ON.</td>
</tr>
<tr>
<td>I</td>
<td>Absolute value low limit alarm</td>
<td>ON H OFF PV 100℃ 90℃ Absolute-value Alarm: Set as 90℃</td>
<td>If PV is lower than the absolute value, the output will be ON.</td>
</tr>
</tbody>
</table>

Sensor break Alarm

It will be ON when it detects sensor disconnection.

Loop break Alarm

It will be ON when it detects loop break.

X: Alarm output hysteresis [HYS]

● Alarm option

<table>
<thead>
<tr>
<th>Mode</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>Standard alarm</td>
<td>If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.</td>
</tr>
<tr>
<td>B</td>
<td>Alarm latch</td>
<td>If it is an alarm condition, alarm output is ON and maintains ON status.</td>
</tr>
<tr>
<td>C</td>
<td>Standby sequence 1</td>
<td>First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.</td>
</tr>
<tr>
<td>D</td>
<td>Alarm latch and standby sequence 1</td>
<td>If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, alarm latch operates.</td>
</tr>
<tr>
<td>E</td>
<td>Standby sequence 2</td>
<td>First alarm condition is ignored and from second alarm condition, standard alarm operates. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.</td>
</tr>
<tr>
<td>F</td>
<td>Alarm latch and standby sequence 2</td>
<td>Basic operation is same as alarm latch and standby sequence 1. It operates not only by power ON/OFF, but also alarm setting value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.</td>
</tr>
</tbody>
</table>

Sensor break alarm

The function that alarm output will be ON when sensor is not connected or when sensor’s disconnection is detected during temperature controlling. You can check whether the sensor is connected with buzzer or other units using alarm output contact. It is selectable between standard alarm [SbA], or alarm latch [LbA].
Loop break alarm (LBA)

It checks control loop and outputs alarm by temperature change of the subject. For heating control (cooling control), when control output MV is 100% (0% for cooling control) and PV is not increased over than LBA detection band [L b Rb] during LBA monitoring time [L b T], or when control output MV is 0% (100% for cooling control) and PV is not decreased below than LBA detection band [L b Rb] during LBA monitoring time [L b T], alarm output turns ON.

Start control to ①
When control output MV is 0% and PV is not decreased below than LBA detection band [L b Rb] during LBA monitoring time [L b T]

① to ② The status of changing control output MV (LBA monitoring time is reset.)
② to ③ When control output MV is 0% and PV is not decreased below than LBA detection band [L b Rb] during LBA monitoring time [L b T] loop break alarm (LBA) turns ON after LBA monitoring time.
③ to ④ Control output MV is 0% and loop break alarm (LBA) turns and maintains ON.
④ to ⑤ The status of changing control output MV (LBA monitoring time is reset.)
⑤ to ⑥ When control output MV is 100% and PV is not increased over than LBA detection band [L b Rb] during LBA monitoring time [L b T] loop break alarm (LBA) turns ON after LBA monitoring time.
⑥ to ⑦ When control output MV is 100% and PV is increased over than LBA detection band [L b Rb] during LBA monitoring time [L b T] loop break alarm (LBA) turns OFF after LBA monitoring time.
⑦ to ⑧ The status of changing control output MV (LBA monitoring time is reset.)
※When executing auto-tuning, LBA detection band [L b Rb] and LBA monitoring time are automatically set based on auto tuning value. When AL1, AL2 alarm operation [AL-1, AL-2] is set as loop break alarm (LBA) [L b Rb], LBA detection band [L b Rb] and LBA monitoring time [L b T] parameter is displayed.

SSR drive output function (SSRP function) [S S r n]

- SSRP function is selectable one of standard ON/OFF control, cycle control, phase control by utilizing standard SSR drive output.
- Realizing high accuracy and cost effective temperature control as linear output(cycle control and phase control).
- Select one of standard ON/OFF control [S S r n], cycle control [S y C C], phase control [P H R S] at [S S r n] parameter of parameter group 2. For cycle control, connect zero cross turn-on SSR or random turn-on SSR. For phase control, connect random turn-on SSR.

※When selecting phase or cycle control mode, the power supply for load and temperature controller must be the same.
※In case of selecting PID control type and phase [P H R S] / cycle [S y C C] control output modes, control cycle [S] is not allowed to set.
※For AC/DC power model (TCN4 22R), this parameter is not displayed and it is available only standard control by relay or SSR.
Dual Display, PID Control

- **Standard ON/OFF control mode [STND]**
  A mode to control the load in the same way as Relay output type.
  (ON: output level 100%, OFF: output level 0%)

- **Cycle control mode [CYCL]**
  A mode to control the load by repeating output ON / OFF according to the rate of output within setting cycle. Having improved ON / OFF noise feature by Zero Cross type.

- **Phase control mode [PHAS]**
  A mode to control the load by controlling the phase within AC half cycle. Serial control is available. RANDOM Turn-on type SSR must be used for this mode.

- **Auto tuning [AT]**
  - Auto tuning measures the control subject's thermal characteristics and thermal response rate, and then determines the necessary PID time constant. (When control type [C - \( \Delta d \)] is set as \( PI \), it is displayed.)
  - If error \( \theta \) occurs during auto tuning, it stops this operation automatically.
  - To stop auto tuning, change the set as OFF. (It maintains P, I, D values of before auto tuning.)

- **Input correction [\( n-b \)]**
  Controller itself does not have errors but there may be error by external input temperature sensor.
  E.g.) If actual temperature is 80°C but controller displays 78°C, set input correction value \( [ n - b ] \) as 02 and controller displays 80°C.
  ※As the result of input correction, if current temperature value (PV) is over each temperature range of input sensor, it displays HHHH or LLLL.

- **Input digital filter [\( R_uF \)]**
  If current temperature (PV) is fluctuating repeatedly by rapid change of input signal, it reflects to MV and stable control is impossible. Therefore, digital filter function stabilizes current temperature value.
  - For example, set input digital filter value as 0.4 sec, and it applies digital filter to input values during 0.4 sec and displays this values. Current temperature may be different by actual input value.

- **SV High/Low limit [H - 5u/L - 5u]**
  - It sets SV high/low limit Limit range of using temperature within temperature range for each sensor, user can set/ change set temperature (SV) within SV high limit [H - 5u] to SV low limit [L - 5u]. ※L - 5u > H - 5u cannot be set.
  - When changing input type [\( n - b \)], SV high limit [H - 5u] and SV low limit [L - 5u] of using temperature will be initialized as max./min. value of sensor temperature range automatically.

- **Hysteresis [HYS]**
  - In case of ON/OFF control, set between ON and OFF intervals as hysteresis. (When control type [C - \( \Delta d \)] is set as \( on\)F, it is displayed.)
  - If hysteresis is too small, it may cause control output hunting (take off, chattering) by external noise, etc.

- **Manual reset [ RESET ]**
  When selecting P/PD control mode, certain temperature difference exists even after PV reaches stable status because heater’s rising and falling time is inconsistent due to thermal characteristics of controlled objects, such as heat capacity, heater capacity. This temperature difference is called offset and manual reset [ RESET ] function is to set/ correct offset.
  - When PV and SV are equal, reset value is 50.0%. After control is stable, PV is lower than SV, reset value is over 50.0% or PV is higher than SV, reset value is below 50.0%.
  - Manual reset [ RESET ] by control result

- **Temperature unit selection [UNIT]**
  A function to select display temperature unit. Unit display indicator will be ON when converting temperature unit.
Cool / Heat function [ \(a - Ft\) ]
Generally there are two ways to control temperature, one (heat-function) is to heat when PV is getting down (heater). The other (cool-function) is to cool when PV is getting higher (freezer).

These functions are operating oppositely when it is ON/OFF control or proportional control. But in this case PID time constant will be different due to PID time constant will be decided according to control system when it is PID control.

- Cool-function \([C_{cool}]\) and heat-function \([H_{ERP}]\) must be set correctly according to the application, if set as opposite function, it may cause a fire. (If set cool-function \([C_{cool}]\) at heater, it will be maintained ON and it may cause a fire.)
- Avoid changing heat-function to cool-function or cool-function to heat-function when the unit is operating.
- It is impossible to operate both function at once in this unit. Therefore, only one function should be selected only.

Control method selection \([t - \tilde{n}d]\)
It is selectable PID, ON/OFF control.

- In case of ON/OFF \([\text{OFF}]\) mode, Hysteresis \([\text{HY5}]\) parameter is displayed.
- In case of PID \([P\ t\ d]\) mode, Proportional band \([P]\), Integral time \([I]\), and Derivative time \([\text{T}\] parameters are displayed.

Control output type selection \([a\ U\ t\] \)
It is selectable output type; relay output \([\text{RLY}]\), SSR drive output \([\text{SSR}]\).

Alarm output hysteresis \([\text{HY5}]\)
It displays alarm output ON and OFF interval and hysteresis is applied to both AL1 OUT and AL2 OUT.

- \(\text{C\ I\ CH}, \text{L\ I\ CH}, \text{C\ EC\ CH}, \text{R\ PR}, \text{S\ PR}, \text{d\ PR}, \text{C\ US\ H}\ : 1\ to\ 100\)
- \(\text{K\ Ca\ H}, \text{J\ Ic\ H}, \text{L\ Ic\ H}, \text{T\ Ca\ H}, \text{D\ Pt\ L}, \text{C\ Us\ L}\ : 0.1\ to\ 50.0\)

E.g.) AL1 alarm operation \([\text{RL - i}]\); AL3AR,
AL1 alarm operation \([\text{RL - i}]\): 10°C,
Alarm output hysteresis \([\text{HY5}]\): 4

Control output MV when input sensor line is broken \([\text{Er\ -\ nu}]\)
When input sensor line is broken or setting value error occurs, this function is to set control output. You can set ON/OFF setting for ON/OFF control, MV setting for PID control.

Digital input key \((\sqrt{7} + \sqrt{3}\ \text{sec})\ \[d\ t\ - \sqrt{7}\])

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>OFF</td>
<td>\text{OFF}</td>
</tr>
<tr>
<td>RUN/STOP</td>
<td>\text{STOP}</td>
</tr>
<tr>
<td>Clear alarm</td>
<td>\text{RL\ -\ E}</td>
</tr>
<tr>
<td>Auto-tuning</td>
<td>\text{AT}</td>
</tr>
</tbody>
</table>

Display
- \text{OFF} Lock off
- \text{LOC1} Lock parameter group 2
- \text{LOC2} Lock parameter group 1, 2
- \text{LOC3} Lock parameter group 1, 2, SV setting

Error
<table>
<thead>
<tr>
<th>Display</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\text{O\ P\ E\ n}</td>
<td>Flashes if input sensor is disconnected or sensor is not connected.</td>
</tr>
<tr>
<td>\text{HHHH}</td>
<td>Flashes if measured sensor input is higher than temperature range.</td>
</tr>
<tr>
<td>\text{LLLL}</td>
<td>Flashes if measured sensor input is lower than temperature range.</td>
</tr>
</tbody>
</table>
© Output connections

● Application of relay output type

Keep A length as long as possible when wiring the temperature controller and the load. If wire length of A is short, counter electromotive force which occurs from a coil of magnet switch & power relay may flow in power line of the unit, and it may cause malfunction.

If wire length of A is short, please connect mylar condensers 104 (630V) on the both ends of “◎” (magnet coil) to protect electromotive force.

■ Simple "error" diagnosis

● When the load (Heater etc) is not operated

Please check operation of the OUT indicator located in front panel of the unit.

If the OUT indicator does not operate, please check the parameter of all programmed mode.

If indicator is operating, please check the output (Relay, SSR drive voltage) after separating output line from the unit.

● When it displays “OPEN” during operation

This is a warning that external sensor is open. Please turn off the power and check the wire state of the sensor. If sensor is not open disconnect sensor line from the unit and short the input +, - terminal. Turn on the power of the unit and check the controller displays room temperature.

If this unit cannot display room temperature, this unit is broken. Please remove this unit and contact our service center. (When the input mode is thermocouple, it is available to display room temperature.)

■ Cautions during use

● Follow instructions in 'Cautions during use'. Otherwise, It may cause unexpected accidents.

● Check the polarity of the terminals before wiring the temperature sensor.

For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length.

For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.

● Keep away from high voltage lines or power lines to prevent inductive noise.

In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

Do not use near the equipment which generates strong magnetic force or high frequency noise.

● Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.

● Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.

● When changing the input sensor, turn off the power first before changing.

After changing the input sensor, modify the value of the corresponding parameter.

● 24VAC, 24-48VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.

● Make a required space around the unit for radiation of heat.

For accurate temperature measurement, warm up the unit over 20 min after turning on the power.

● Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.

● Do not wire to terminals which are not used.

● This unit may be used in the following environments.

1. Indoors (in the environment condition rated in 'Specifications')
2. Altitude max. 2,000m
3. Pollution degree 2
4. Installation category II